

BÖLÜM 10

RADYAL DENKLEM

$$\left(\frac{d^2}{dr^2} + \frac{2}{r} \frac{d}{dr} \right) R_{nl}(r) - \frac{2\mu}{\hbar^2} \left[V(r) + \frac{l(l+1)\hbar^2}{2\mu r^2} \right] R_{nl}(r) + \frac{2\mu E}{\hbar^2} R_{nl}(r) = 0$$

- Denklemin bağımlılığı yok, böylece verilen l için $(2l+1)$ katlı dejenerelik var.

Coulomb pot. hariç, $1/r$ den daha hızlı sifira giden pot. ler için bu denklemi çözeceğiz. Ve orijinal,

$$\lim_{r \rightarrow 0} r^2 V(r) = 0$$

varsayacağız.

$$u_{nl}(r) = r R_{nl}(r)$$

dönüşümünü yapalım. O zaman

$$\left(\frac{d^2}{dr^2} + \frac{2}{r} \frac{d}{dr} \right) \frac{u_{nl}}{r} = \frac{1}{r} \frac{d^2 u}{dr^2}$$

$$\frac{d}{dr} \frac{u}{r} = -\frac{1}{r^2} u + \frac{1}{r} \frac{du}{dr} \Rightarrow \frac{d^2}{dr^2} \frac{u}{r} = \frac{2}{r^3} u - \frac{1}{r^2} \frac{du}{dr}$$

$$-\frac{1}{r^2} \frac{du}{dr} + \frac{1}{r} \frac{d^2 u}{dr^2}$$

$$\frac{2}{r^3} u + \frac{1}{r} \frac{d^2 u}{dr^2} + \frac{2}{r^2} \frac{du}{dr} - \frac{2}{r^3} u$$

$$\frac{1}{r} \frac{d^2 u_{nl}}{dr^2} + \frac{2\mu}{\hbar^2} \left[E - V(r) - \frac{l(l+1)\hbar^2}{2\mu r^2} \right] \frac{u_{nl}(r)}{r} = 0$$

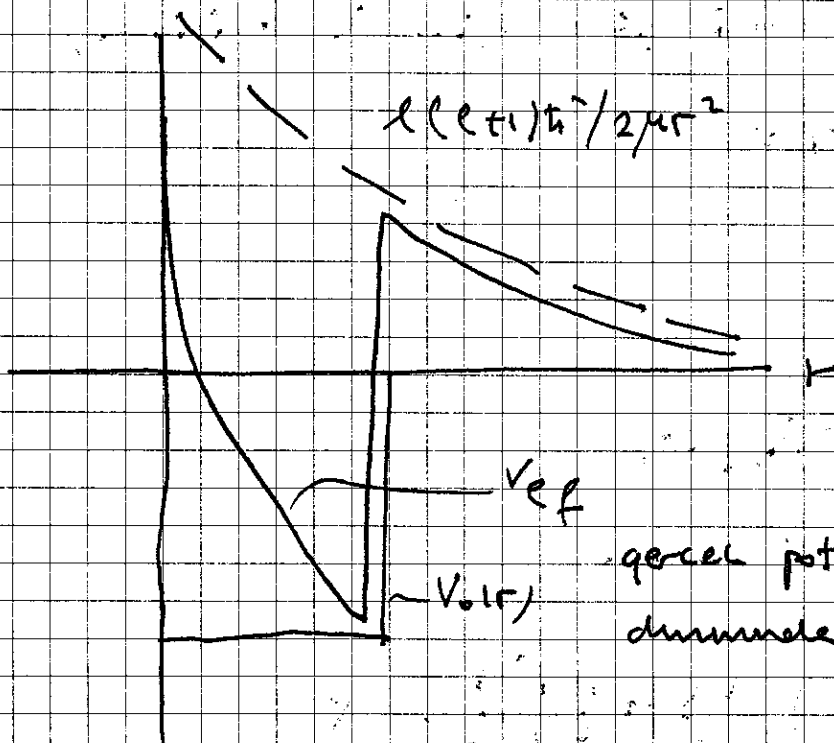
(a)

$$V(r) \rightarrow V(r) + \frac{l(l+1)\hbar^2}{2\mu r^2}$$

(b) Original dalga funksi'yunu qoruyub almaq

$$u_{nl}(0) = 0$$

qoruyub almaq

qoruyub almaq pot. 'il kənar kənar olmağı
dərəcəsi

6) $r \rightarrow 0$ civarında çözüme bakalım, burada etki terim $1/r^2$ dir.

$$\frac{d^2 u}{dr^2} - \frac{l(l+1)}{r^2} u \approx 0$$

Çözüm önerisi $u(r) \sim r^s$

$$s(s-1) - l(l+1) = 0 \Rightarrow \begin{cases} s = l+1 & u \sim r^{l+1} \text{ dirim} \\ s = -l & u \sim r^{-l} \text{ mülki} \end{cases}$$

($u(0) = 0$ için)

$r \rightarrow \infty$ iken

$$\frac{d^2 u}{dr^2} + \frac{2\mu E}{\hbar^2} u \approx 0$$

normalizasyon şartı

$$1 = \int d^3 \vec{r} |\psi(\vec{r})|^2 = \int_0^\infty r^2 dr \int d\Omega |R_{nl}(r) Y_{lm}|^2$$

$$\Rightarrow \int_0^\infty |r R_{nl}|^2 dr = 1$$

$$\int_0^\infty |u_{nl}|^2 dr = 1 \Rightarrow u \rightarrow 0 \text{ olmalı, } r \rightarrow \infty \text{ iken}$$

$$\frac{2\mu E}{\hbar^2} = -\alpha^2 \text{ alırsak} \quad E < 0$$

$$u(r) \sim e^{-\alpha r} \text{ ıraksamaz.}$$

$$\frac{2\mu E}{\hbar^2} = k^2 \text{ alırsak} \quad E > 0$$

$$u(r) \sim e^{\pm ikr}$$

A SERBEST PARÇACIK

$V(r) = 0$ ama hala $\frac{\ell(\ell+1)\hbar^2}{2\mu r^2}$ merkezkaç engeli mevcut.

$$\left[\frac{d^2}{dr^2} + \frac{2}{r} \frac{d}{dr} - \frac{\ell(\ell+1)}{r^2} \right] R(r) + k^2 R(r) = 0$$

$$k^2 = 2\mu E / \hbar^2$$

$\rho = kr$ dönüşümü yapalım.

$$\frac{d}{dr} = \frac{d\rho}{dr} \frac{d}{d\rho} = k \frac{d}{d\rho}$$

$$\frac{d^2}{dr^2} = k \frac{d}{dr} \frac{d\rho}{d\rho} = k^2 \frac{d^2}{d\rho^2}$$

$$\left[k^2 \frac{d^2}{d\rho^2} + \frac{2}{\rho} k \frac{d}{d\rho} - \frac{\ell(\ell+1)}{\rho^2} k^2 \right] R + k^2 R = 0$$

$$\left[\frac{d^2}{d\rho^2} + \frac{2}{\rho} \frac{d}{d\rho} - \frac{\ell(\ell+1)}{\rho^2} \right] R + R = 0$$

$$\frac{d^2 u}{d\rho^2} + \frac{2}{\rho} \frac{du}{d\rho} - \frac{\ell(\ell+1)}{\rho^2} u + u = 0$$

$$R=0 \Rightarrow \frac{d^2 u}{d\rho^2} + \frac{2}{\rho} \frac{du}{d\rho} + u = 0$$

$u = rR$ dönüşümü yapalım.

$$\frac{dR}{dr} = -\frac{1}{r^2} u + \frac{1}{r} \frac{du}{dr}$$

$$\begin{aligned} \frac{d^2 R}{dr^2} &= \frac{2}{r^3} u - \frac{1}{r^2} \frac{du}{dr} - \frac{1}{r^2} \frac{du}{dr} + \frac{1}{r} \frac{d^2 u}{dr^2} \\ &= \frac{2}{r^3} u - \frac{2}{r^2} \frac{du}{dr} + \frac{1}{r} \frac{d^2 u}{dr^2} \end{aligned}$$

$$\begin{aligned} &\frac{2}{r^3} u - \frac{2}{r^2} \frac{du}{dr} + \frac{1}{r} \frac{d^2 u}{dr^2} + \frac{2}{r} \frac{d}{dr} \left(\frac{u}{r} \right) - \frac{l(l+1)}{r^2} \frac{u}{r} \\ &+ \frac{u}{r} = 0 \end{aligned}$$

$$\boxed{\frac{d^2 u}{dr^2} - \frac{l(l+1)}{r^2} u + u = 0}$$

$$l=0 \Rightarrow \frac{d^2 u}{dr^2} + u = 0 \quad \left\{ \begin{array}{l} u(r) \sim \sin r \\ \cos r \end{array} \right.$$

$$R \sim \left\{ \begin{array}{l} \frac{\sin r}{r} \quad \leftarrow \text{düzgün görün} \\ \frac{\cos r}{r} \quad \leftarrow \text{düzgün olmayan görün.} \end{array} \right.$$

$$\rho^2 \frac{d^2 R}{d\rho^2} + 2\rho \frac{dR}{d\rho} + (\rho^2 - \ell(\ell+1)) R = 0$$

bu den çözümünü küresel Bessel fon. 'larıdır.

$$R(\rho) = \frac{u(\rho)}{\rho} \quad \text{değişimni yapalım.}$$

$$R' = u' \rho^{-1/2} - \frac{1}{2} \rho^{-3/2} u$$

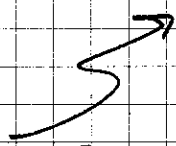
$$\begin{aligned} R'' &= u'' \rho^{-1/2} - \frac{1}{2} \rho^{-3/2} u' - \frac{1}{2} \rho^{-3/2} u' + \frac{3}{4} \rho^{-5/2} u \\ &= u'' \rho^{-1/2} - \rho^{-3/2} u' + \frac{3}{4} \rho^{-5/2} u \end{aligned}$$

$$\Rightarrow \rho^2 R'' = u'' \rho^{3/2} - u' \rho^{1/2} + \frac{3}{4} u \rho^{-1/2}$$

$$2\rho R' = 2u' \rho^{1/2} - 2u \rho^{-1/2}$$

$$\begin{aligned} &+ \rho^2 u'' - \rho^2 u' \rho^{-1/2} + \rho^2 u' \rho^{-3/2} + \rho^2 \frac{3}{4} u \rho^{-5/2} \\ &+ 2\rho u' \rho^{-1/2} + 2\rho \left(-\frac{1}{2}\right) u \rho^{-3/2} + (\rho^2 - \ell(\ell+1)) u \rho^{-1/2} = 0 \\ &\rho^2 u'' - \rho u' + \frac{3}{4} u + 2\rho u' - u + (\rho^2 - \ell(\ell+1)) u = 0 \\ &\rho^2 u'' + \rho u' + \left[\rho^2 - \ell(\ell+1) - \frac{1}{4}\right] u = 0 \end{aligned}$$

$$p^2 u'' + p u' + \left[p^2 - \left(l + \frac{1}{2} \right)^2 \right] u = 0$$



Bunun çözümleri $J_{l+1/2}(p)$ ve $N_{l+1/2}(p)$

$$R(p) = \frac{c_1}{\sqrt{p}} J_{l+1/2}(p) + \frac{c_2}{\sqrt{p}} N_{l+1/2}(p)$$

$$= c \dot{j}_l(p) + c' n_l(p)$$

$$\dot{j}_l(p) = \sqrt{\frac{\pi}{2p}} J_{l+\frac{1}{2}}(p)$$

$$n_l(p) = \sqrt{\frac{\pi}{2p}} N_{l+\frac{1}{2}}(p)$$

Rekürans bağıntısı: $\frac{\dot{j}_{l+1}}{p^{l+1}} = -\frac{1}{p} \frac{d}{dp} \left(\frac{\dot{j}_l}{p^l} \right)$

$l=0$ $\frac{\dot{j}_1}{p} = -\frac{1}{p} \frac{d}{dp} \dot{j}_0$

$l=1$ $\frac{\dot{j}_2}{p^2} = -\frac{1}{p} \frac{d}{dp} \left(\frac{\dot{j}_1}{p} \right) = -\frac{1}{p} \frac{d}{dp} \left(-\frac{1}{p} \frac{d}{dp} \dot{j}_0 \right)$

$\vdots$
 $l-1$ defa $\dot{j}_l(p) = (-p)^l \left(\frac{1}{p} \frac{d}{dp} \right)^l \dot{j}_0$

BS $K \dot{j}_0 = \sin p / p$

$$\dot{z}_0(p) = \frac{\sin p}{p}$$

$$\dot{z}_1(p) = \frac{\sin p}{p^2} - \frac{\cos p}{p}$$

$$\dot{z}_2(p) = \left(\frac{2}{p^3} - \frac{1}{p} \right) \sin p - \frac{2}{p^2} \cos p$$

$$w_e(p) = -(-p)^p \left(\frac{1}{p} \frac{d}{dp} \right)^p \frac{\cos p}{p}$$

Bunların bilesimleri,

$$h_p^{(1)}(p) = \dot{z}_e(p) + i w_e(p)$$

küresel Hankel Fark.

$$h_e^{(2)}(p) = \dot{z}_e(p) - i w_e(p)$$

$$h_0^{(1)}(p) = \frac{e^{ip}}{ip} \quad h_1^{(1)} = -\frac{e^{ip}}{p} \left(1 + \frac{i}{p} \right)$$

$$h_2^{(1)}(p) = i \frac{e^{ip}}{p} \left(1 + \frac{3i}{p} - \frac{3}{p^3} \right)$$

(a) Orijin civarındaki davranış: $\rho \ll \ell$ için

$$j_\ell(\rho) \approx \frac{\rho^\ell}{1 \cdot 3 \cdot 5 \cdot \dots \cdot (2\ell+1)}$$

$$n_\ell(\rho) \approx - \frac{1 \cdot 3 \cdot 5 \cdot \dots \cdot (2\ell-1)}{\rho^{\ell+1}}$$

$\rho \gg \ell$ için $j_\ell(\rho) \approx \frac{1}{\rho} \sin\left(\rho - \frac{\ell\pi}{2}\right)$

$$R(\rho) = j_\ell(k\rho)$$

$$= -\frac{1}{2i k r} \left[e^{-i\left(kr - \frac{\ell\pi}{2}\right)} - e^{+i\left(kr + \frac{\ell\pi}{2}\right)} \right]$$

B. KARE KUTU, BAĞLI DURUMLAR

$$V(r) = \begin{cases} -V_0 & r < a \\ 0 & r > a \end{cases}$$

$$\frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} - \frac{l(l+1)}{r^2} R + \frac{2\mu}{\hbar^2} (V_0 + E) R = 0 \quad r < a$$

$$\frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} - \frac{l(l+1)}{r^2} R + \frac{2\mu E}{\hbar^2} R = 0 \quad r > a$$

$$-k^2 = (i\alpha)^2 \text{ olarak}$$

$E < 0$ olan bağlı durum çözümlerini bulalım. $k \rightarrow i\alpha$
Renel V_0 dur.

$$\frac{2\mu}{\hbar^2} (V_0 + E) = -k^2$$

$$\frac{2\mu}{\hbar^2} E = -\alpha^2$$

$r < a$ için $R(r) = A j_l(kr)$ başlangıç noktasında düzenli olman için.

$r > a$ çözümü $r \rightarrow \infty$ için 0 olmalıdır.

$k \rightarrow i\alpha$ sonrasında e^{ikr} gibi davranışa gireli $e^{-\alpha r}$ olur.

$$R(r) = B h_e^{(1)}(i\alpha r)$$

iki çözüm ve türevleri $r=a$ 'da eşitlenir.

$$\frac{d}{dr} j_p(s) = \kappa \frac{d}{ds} j_p(s)$$

$$\kappa \left[\frac{dj_p(s)/ds}{j_p(s)} \right]_{s=\kappa a} = i\alpha \left[\frac{dh_p^{(1)}(r)/dr}{h_p^{(1)}(r)} \right]_{r=i\alpha a}$$

ℓ , V_0 ve F için çok karmaşık bir denklemdir.

$\ell \equiv 0$ için basit çözüm.

$$\frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} + \kappa^2 R = 0 \quad r < a$$

$$\frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} - \alpha^2 R = 0 \quad r > a$$

$$R(r) = \frac{u(r)}{r} \quad \text{dönüştürme yapalım}$$

$$\frac{d^2 u}{dr^2} + \kappa^2 u = 0 \quad r < a \quad u(r) = A \sin \kappa r + B \cos \kappa r$$

$$\frac{d^2 u}{dr^2} - \alpha^2 u = 0 \quad r > a \quad u(r) = C e^{-\alpha r} + D e^{\alpha r}$$

$$r=a \text{ 'da} \quad \left. \frac{\kappa A \cos \kappa r}{A \sin \kappa r} \right|_{r=a} = \left. \frac{-\alpha C e^{-\alpha r}}{C e^{-\alpha r}} \right|_{r=a}$$

$$\gamma \cot \gamma a = -\alpha \quad / \quad a$$

$$a \gamma \cot \gamma a = -\alpha a$$

$$a \gamma = \zeta$$

$$a \alpha = \xi$$

$$\gamma \cot \gamma = -\xi$$

$$\gamma^2 + \xi^2$$

$$\frac{2\mu}{\hbar^2} (V_0 + E) = \gamma^2$$

$$\frac{2\mu}{\hbar^2} E = -\alpha^2$$

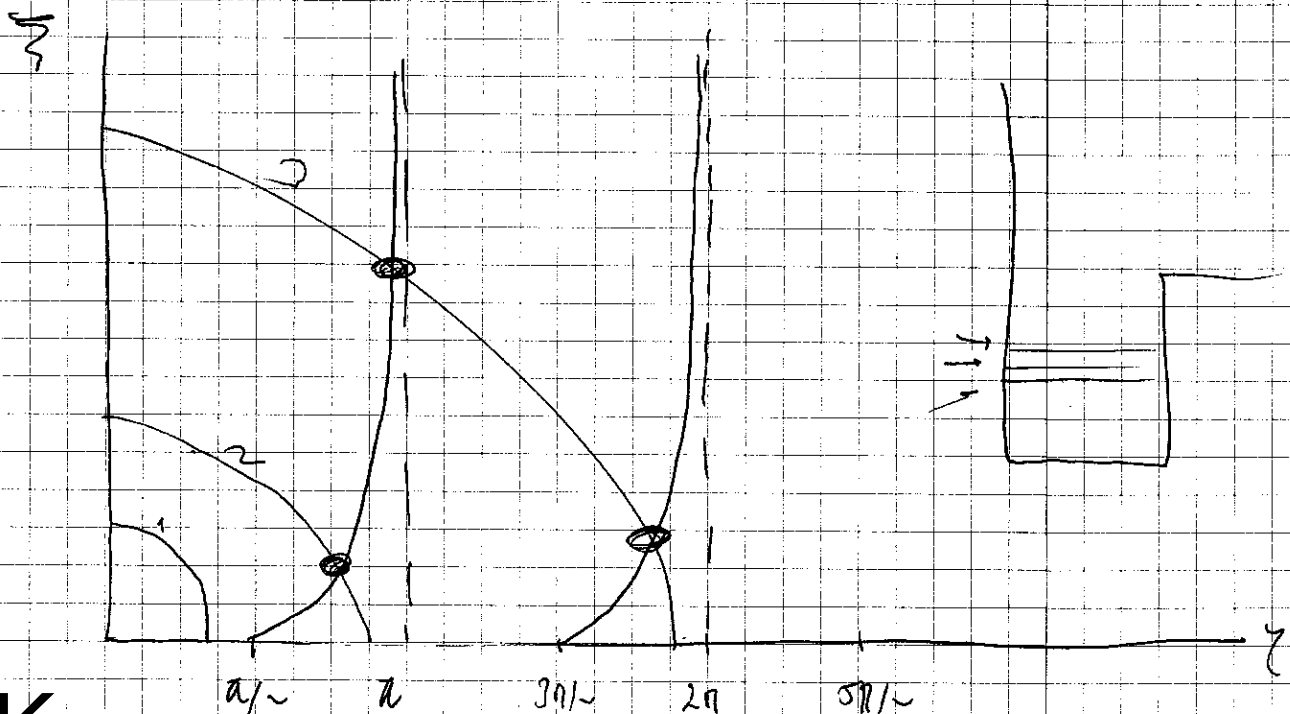
$$-\alpha^2 + \frac{2\mu}{\hbar^2} V_0 = \gamma^2$$

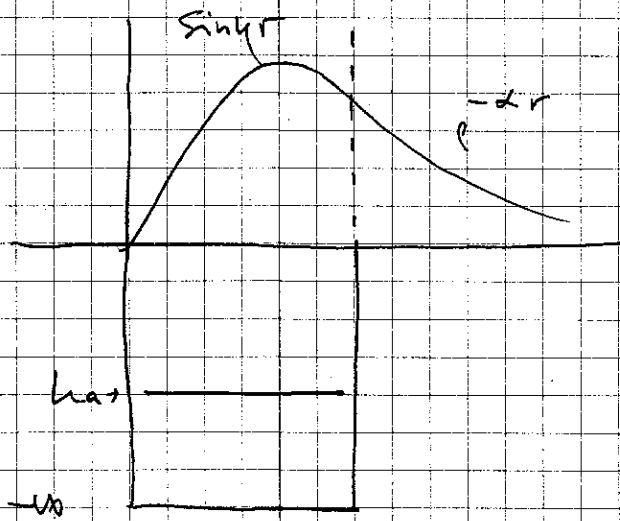
$$\alpha^2 + \gamma^2 = \frac{2\mu V_0}{\hbar^2}$$

$$/ \quad a^2$$

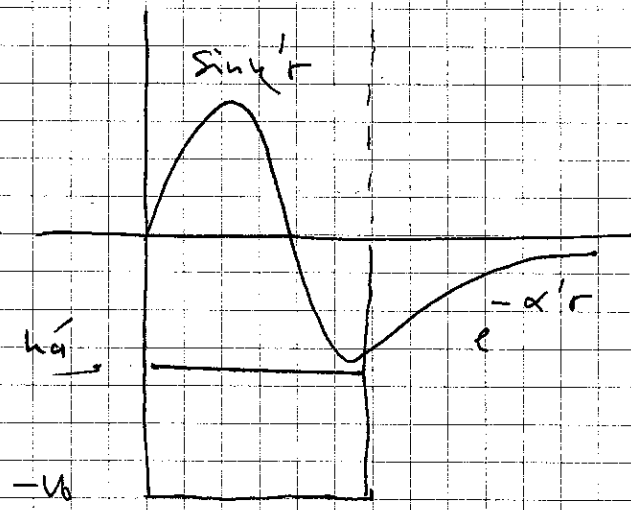
$$\gamma^2 + \xi^2 = \frac{2\mu V_0}{\hbar^2} a^2 = W^2$$

çember denklemini





1. bağılı durum



2. bağılı durum

• Bağılı durum olabilmeleri için

$$\frac{2\mu V_0}{\hbar^2} a^2 > \frac{\pi^2}{4} \text{ olmalı.}$$

• Enerji Kuyusu: Sürekli Çözümler

$$E > 0 \text{ durumunda } \frac{2\mu E}{\hbar^2} = k^2$$

$$\sigma < a \quad \text{N} \quad R_{\sigma}(r) = A j_{\sigma}(kr) \quad \text{İçeride}$$

$$\sigma > a \quad \vee \quad R_{\sigma}(r) = B j_{\sigma}(kr) + C n_{\sigma}(kr) \text{ olur.}$$

$$k^2 = \frac{2\mu}{\hbar^2} (E + V_0)$$

$$\sigma = a \text{ 'da } \vee \left[\frac{d j_{\sigma}(p)/dp}{j_{\sigma}(p)} \right]_{p=k} = k \left[\frac{B d j_{\sigma}/dp + C d n_{\sigma}/dp}{B j_{\sigma}(p) + C n_{\sigma}(p)} \right]_{p=ka}$$

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$\frac{C}{B}$ oranını faz kayması olarak yorumlayacağız. $J_p(r)$ ve $n_p(r)$ 'nin asimptotik değerlerle sakanz ($r > a$ için)

$$R_p(r) = \frac{B}{kr} \left[\sin\left(kr - \frac{l\pi}{2}\right) - \frac{C}{B} \cos\left(kr - \frac{l\pi}{2}\right) \right]$$

$$\frac{C}{B} = -\tan \delta_l(k) \text{ denek,}$$

$$R_p(r) = \frac{B}{kr} \frac{1}{\cos \delta_l(k)} \left[\sin\left(kr - \frac{l\pi}{2}\right) \cos \delta_l(k) + \cos\left(kr - \frac{l\pi}{2}\right) \sin \delta_l(k) \right]$$

$$= \frac{C'}{r} \sin\left(kr - \frac{l\pi}{2} + \delta_l(k)\right)$$

$l=0$ için $u(r) = r R(r)$ değişimini yaptığımızda

$$u(r) = A \sin kr \quad r < a$$

$$u(r) = B \sin kr + C \cos kr \quad r > a$$

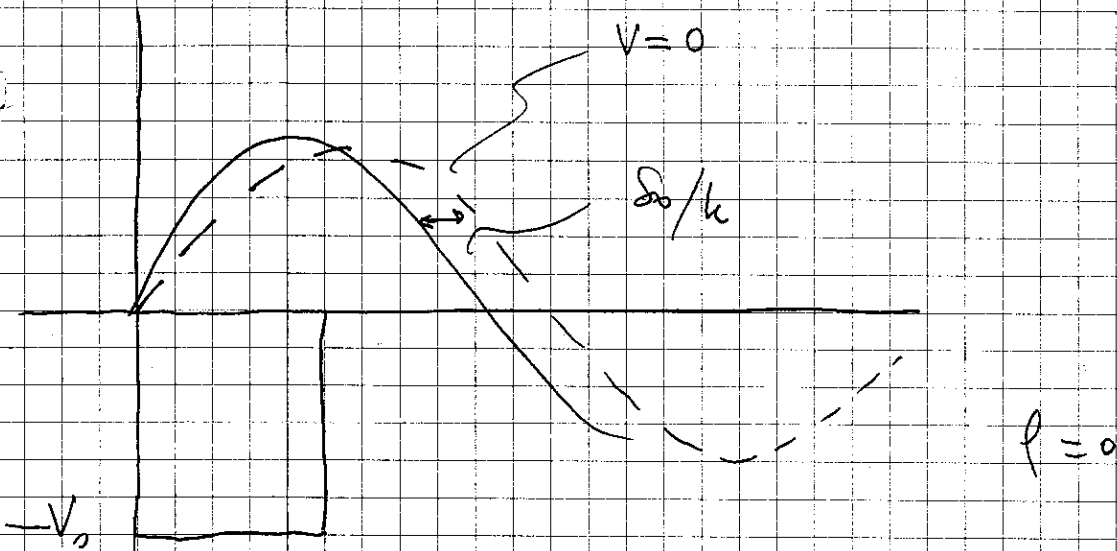
$$\gamma \frac{\cos \gamma a}{\sin \gamma a} = k \frac{B \cos ka - C \sin ka}{B \sin ka + C \cos ka}$$

$$\gamma \cot \gamma a = k \frac{\cos ka - \frac{C}{B} \sin ka}{\sin ka + \frac{C}{B} \cos ka} \quad \frac{C}{B} = \tan \delta_0$$

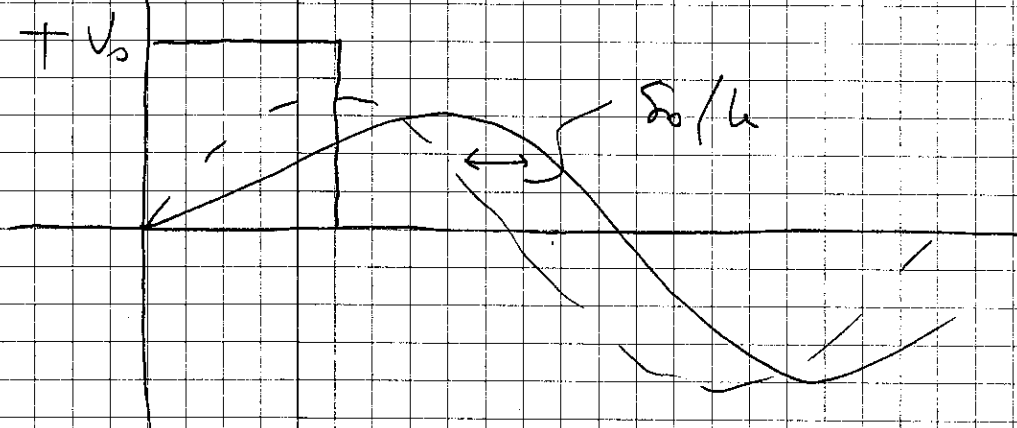
$$y \cot y a = k \frac{\cos (k a + \delta_0)}{\sin (k a + \delta_0)} = k \cot (k a + \delta_0)$$

$$\tan (k a + \delta_0) = \frac{k}{y} \tan y a$$

$$\delta_0 = -k a + n\pi + \text{Arctan} \left(\frac{k}{y} \tan y a \right)$$



Sayıma π ve
geri dönülecek.



D. Kuntü içi hâzeli Parçacık:

$$V(r) = \begin{cases} 0 & r < R \\ \infty & r > R \end{cases}$$

$$k^2 = 2\mu E / \hbar^2$$

$$\frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} - \frac{l(l+1)}{r^2} R + \frac{2\mu E}{\hbar^2} R = 0 \quad r < R$$

$$R(r) = 0 \quad r > R$$

$$u = rR$$

$$\frac{dR}{dr} = -\frac{1}{r^2} u + \frac{1}{r} \frac{du}{dr}$$

$$\begin{aligned} \frac{d^2 R}{dr^2} &= \frac{2}{r^3} u - \frac{1}{r^2} u' - \frac{1}{r^2} u' + \frac{1}{r} \frac{d^2 u}{dr^2} \\ &= \frac{2}{r^3} u - \frac{2}{r^2} u' + \frac{1}{r} u'' \end{aligned}$$

$$\frac{2}{r^3} u - \frac{2}{r^2} u' + \frac{1}{r} u'' + \frac{2}{r} \left(-\frac{1}{r^2} u + \frac{1}{r} u' \right) - \frac{l(l+1)}{r^3} u + k^2 \frac{u}{r} = 0$$

$$\frac{1}{r} u'' - \frac{l(l+1)}{r^3} u + k^2 \frac{u}{r} = 0$$

$$u'' + \left(k^2 - \frac{l(l+1)}{r^2} \right) u = 0$$

2.)

$$u = z^{1/2} \phi(z)$$

1.)

$$z = kr$$

$$\frac{d}{dr} = \frac{dz}{dr} \frac{d}{dz} = k \frac{d}{dz} \quad \frac{d^2}{dr^2} = k^2 \frac{d^2}{dz^2}$$

$$k^2 \frac{d^2 u}{dz^2} + \left(k^2 - \frac{\ell(\ell+1)}{r^2} \right) u = 0$$

$$\frac{d^2 u}{dz^2} + \left(1 - \frac{\ell(\ell+1)}{z^2} \right) u = 0$$

$$\frac{du}{dz} = \frac{1}{2} z^{-1/2} \varphi + z^{1/2} \varphi'$$

$$\begin{aligned} \frac{d^2 u}{dz^2} &= -\frac{1}{4} z^{-3/2} \varphi + \frac{1}{2} z^{-1/2} \varphi' + \frac{1}{2} z^{-1/2} \varphi' + z^{1/2} \varphi'' \\ &= z^{1/2} \varphi'' + z^{-1/2} \varphi' - \frac{1}{4} z^{-3/2} \varphi \end{aligned}$$

$$z^{1/2} \varphi'' + z^{-1/2} \varphi' - \frac{1}{4} z^{-3/2} \varphi + \left[1 - \frac{\ell(\ell+1)}{z^2} \right] z^{1/2} \varphi = 0$$

$$\varphi'' + \frac{1}{z} \varphi' + \left[-\frac{1}{4z^2} + 1 - \frac{\ell(\ell+1)}{z^2} \right] \varphi = 0$$

$$\begin{aligned} 1 - \frac{\ell(\ell+1) + 1/4}{z^2} &= 1 - \frac{\ell^2 + \ell + 1/4}{z^2} \\ &= 1 - \frac{(\ell + \frac{1}{2})^2}{z^2} \end{aligned}$$

$$\varphi'' + \frac{1}{z} \varphi' + \left[1 - \frac{(\ell + \frac{1}{2})^2}{z^2} \right] \varphi = 0$$

$$\phi(z) = C_1 J_{\ell+1/2}(z) + C_2 J_{-(\ell+1/2)}(z)$$

$$j_\ell(z) = \sqrt{\frac{Rz}{2}} J_{\ell+1/2}(z)$$

$$n_\ell(z) = (-1)^{\ell+1} \sqrt{\frac{Rz}{2}} J_{-(\ell+1/2)}(z)$$

$$u(z) = z^{1/2} \left[C_1 J_{\ell+1/2} + C_2 J_{-(\ell+1/2)} \right]$$

$$= C_1' j_\ell + C_2' n_\ell$$

$$R(r) = \frac{u(kr)}{kr} = \frac{1}{r} \left(C_1'' j_\ell(kr) + C_2'' n_\ell(kr) \right)$$

alternativ

$r=0$ da $\sigma = -\ell$

geschützt inalter

$$R(r) = \frac{C_1''}{r} j_\ell(kr)$$

$$r=R \text{ da } R(r=R)=0 \Rightarrow j_\ell(kR)=0$$

$$\Rightarrow J_{\ell+1/2}(kR)=0$$

Wählen beliebig

ter $l + \frac{1}{2}$ için Bessel fonk. 'u aynı sayıda sıfırlara sahip.

Her bir l için sıfırların sayısı $n_r = 1, 2, 3, \dots$ radial kuantum sayısı ile eşit enerji

$$E_{n_r, l} = \frac{\hbar^2}{2m} k_{n_r, l}^2$$

$$j_0(z) = \sin z \text{ için } j_1(z) = \frac{\sin z}{z} - \cos z$$

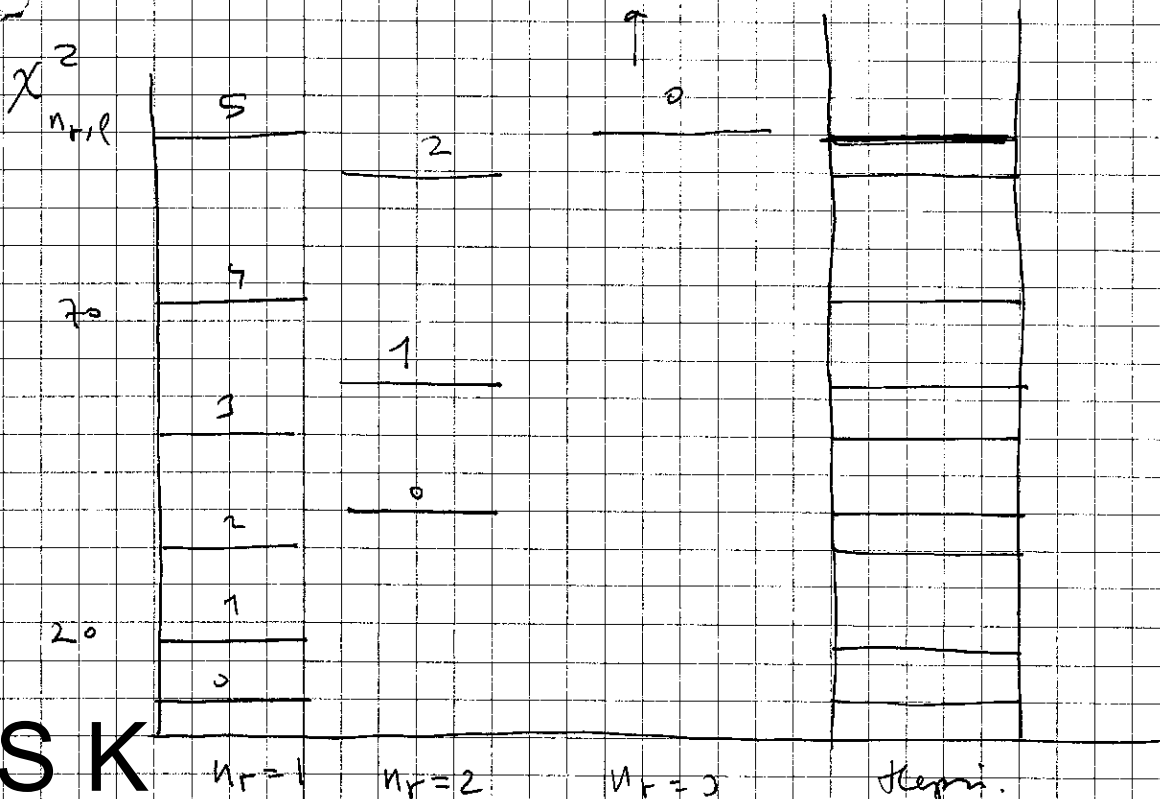
$$j_0(z) = 0 \Rightarrow \sin z = 0 \Rightarrow z = n_r \pi$$

$$j_1(z) = 0 \Rightarrow \tan z = z, \dots$$

tercihi çift l 'ler için $n\pi$

tercihi tek l 'ler için $(l + 1/2)$ ye gider.

$$\chi_{n_r, l} = k_{n_r, l} R \text{ demek}$$



n	1	2	3	4
0	3.142	6.283	9.425	12.566
1	4.493	7.725	10.907	
2	5.767	9.095	12.320	
3	6.988	10.417		

$$H = \frac{\vec{p}_1^2}{2m_1} + \frac{\vec{p}_2^2}{2m_2} + V(\vec{r}_1, \vec{r}_2) \quad V(\vec{r}_1, \vec{r}_2) = V(|\vec{r}_1 - \vec{r}_2|) \text{ olan}$$

$$\int \vec{r}_1 \rightarrow \vec{r}_1 + \vec{a} \quad \vec{r}_2 \rightarrow \vec{r}_2 + \vec{a} \text{ yarağıstımeleri altına değıtmen}$$

$$- \hbar^2 \left(\frac{1}{2m_1} \nabla_1^2 + \frac{1}{2m_2} \nabla_2^2 \right) \psi(\vec{r}_1, \vec{r}_2) = V(|\vec{r}_1 - \vec{r}_2|) \psi(\vec{r}_1, \vec{r}_2) = E \psi(\vec{r}_1, \vec{r}_2)$$

$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$$

$$\vec{r} = \vec{r}_1 - \vec{r}_2$$

$$\vec{r}_1 = m_2 \vec{R} + m_1 \vec{r} \quad X = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}, \quad Y = \frac{m_1 y_1 + m_2 y_2}{m_1 + m_2}, \quad Z = \frac{m_1 z_1 + m_2 z_2}{m_1 + m_2}$$

$$x_1(x, X) \quad x_2(x, X) \text{ koordinat değıřimlerini yapalım.}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} X \\ -X \end{pmatrix}$$

$$\frac{\partial}{\partial x_1} = \frac{\partial}{\partial X} \frac{\partial X}{\partial x_1} + \frac{\partial}{\partial x} \frac{\partial x}{\partial x_1} = \frac{m_1}{m_1 + m_2} \frac{\partial}{\partial X} + \frac{\partial}{\partial x}$$

$$\frac{\partial^2}{\partial x_1^2} = \frac{\partial}{\partial x_1} \left[\frac{m_1}{m_1 + m_2} \frac{\partial}{\partial X} + \frac{\partial}{\partial x} \right] = \left[\frac{m_1}{m_1 + m_2} \frac{\partial}{\partial X} + \frac{\partial}{\partial x} \right] \left[\frac{m_1}{m_1 + m_2} \frac{\partial}{\partial X} + \frac{\partial}{\partial x} \right]$$

$$= \left(\frac{m_1}{m_1 + m_2} \right)^2 \frac{\partial^2}{\partial X^2} + \frac{\partial^2}{\partial x^2} + 2 \frac{m_1}{m_1 + m_2} \frac{\partial^2}{\partial X \partial x} \quad \times \frac{1}{2m_1}$$

$$\frac{\partial^2}{\partial x_2^2} = \left(\frac{m_2}{m_1 + m_2} \right)^2 \frac{\partial^2}{\partial X^2} + \frac{\partial^2}{\partial x^2} + 2 \frac{m_2}{m_1 + m_2} \frac{\partial^2}{\partial X \partial x} \quad \times \frac{1}{2m_2}$$

$$\frac{1}{2m_1} \frac{\partial^2}{\partial x_1^2} + \frac{1}{2m_2} \frac{\partial^2}{\partial x_2^2} = \frac{(m_1 + m_2)}{2(m_1 + m_2)^2} \frac{\partial^2}{\partial X^2} + \frac{1}{2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right) \frac{\partial^2}{\partial x^2} = \frac{1}{2M} \frac{\partial^2}{\partial X^2} + \frac{1}{2\mu} \frac{\partial^2}{\partial x^2}$$

6.

$$\vec{p} \rightarrow -\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) - \frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

$$\left[-\frac{\hbar^2}{2m} \left(\nabla_{\vec{R}}^2 + \nabla_{\vec{r}}^2 \right) + V(\vec{r}) \right] \psi(\vec{R}, \vec{r}) = E \psi(\vec{R}, \vec{r})$$

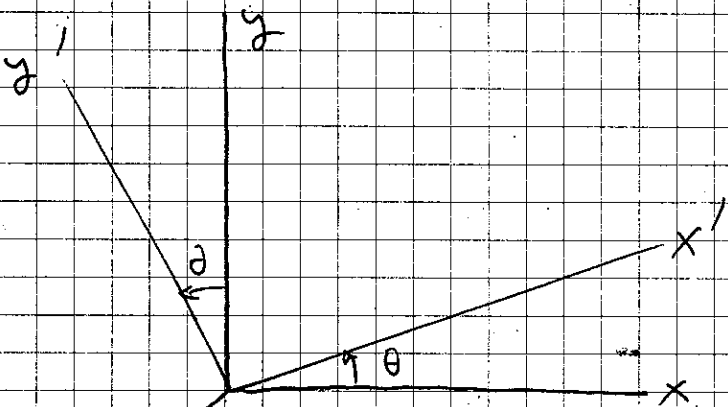
$$\psi(\vec{R}, \vec{r}) = \Phi(\vec{R}) \phi(\vec{r})$$

$$\left[-\frac{\hbar^2}{2m} \nabla_{\vec{R}}^2 \Phi(\vec{R}) = E_1 \Phi(\vec{R}) \right]$$

$$\Rightarrow \psi(\vec{R}, \vec{r}) = \Phi(\vec{r}) e^{i \vec{k} \cdot \vec{R}}$$

$$\left[-\frac{\hbar^2}{2\mu} \nabla_{\vec{r}}^2 + V(\vec{r}) \right] \phi(\vec{r}) = E_2 \phi(\vec{r})$$

Hamiltoniyeri dönmeler altında değişmezdir. Bu -
görmek için 2-eksenli dairesel dönüşü ele alalım.



$$x' = x \cos \theta + y \sin \theta$$

$$y' = -x \sin \theta + y \cos \theta$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\frac{\partial}{\partial x} = \frac{\partial x'}{\partial x} \frac{\partial}{\partial x'} + \frac{\partial y'}{\partial x} \frac{\partial}{\partial y'} = \cos \theta \frac{\partial}{\partial x'} - \sin \theta \frac{\partial}{\partial y'}$$

$$\frac{\partial^2}{\partial x^2} = \cos \theta \frac{\partial}{\partial x} \left(\frac{\partial}{\partial x'} \right) - \sin \theta \frac{\partial}{\partial x} \left(\frac{\partial}{\partial y'} \right)$$

$$= \cos \theta \left(\cos \theta \frac{\partial}{\partial x'} - \sin \theta \frac{\partial}{\partial y'} \right) \frac{\partial}{\partial x'} - \sin \theta \left(\cos \theta \frac{\partial}{\partial x'} - \sin \theta \frac{\partial}{\partial y'} \right) \frac{\partial}{\partial y'}$$

$$= \cos^2 \theta \frac{\partial^2}{\partial x'^2} - 2 \cos \theta \sin \theta \frac{\partial^2}{\partial x' \partial y'} + \sin^2 \theta \frac{\partial^2}{\partial y'^2}$$

$$\bigcirc \frac{\partial^2}{\partial y^2} = \sin^2 \theta \frac{\partial^2}{\partial x'^2} + 2 \cos \theta \sin \theta \frac{\partial^2}{\partial x' \partial y'} + \cos^2 \theta \frac{\partial^2}{\partial y'^2}$$

$\nabla^2 = \nabla'^2$ Längenaltere desigieren $\vec{r}$ ler de räumlichen

ertheilungen berechnet. Sonst hiesst räumliche Altere

$$\begin{pmatrix} x' = x + y\theta \\ y' = y - x\theta \end{pmatrix}$$

$$\begin{aligned} \cos \theta &\approx 1 \\ \sin \theta &\approx \theta \end{aligned}$$

$$\phi(x + y\theta, y - x\theta, z) = \phi(x, y, z) + y\theta \frac{\partial \phi}{\partial x} - x\theta \frac{\partial \phi}{\partial y} + \dots$$

$$\mathbb{E} \left[\phi(x, y, z) + y\theta \frac{\partial \phi}{\partial x} - x\theta \frac{\partial \phi}{\partial y} + \dots \right] = \mathbb{E} \left[\phi(x, y, z) + y\theta \frac{\partial \phi}{\partial x} - x\theta \frac{\partial \phi}{\partial y} + \dots \right]$$

$$\mathbb{E} \phi(x, y, z) = \mathbb{E} \phi(x, y, z)$$

BS K $\mathbb{E} \left[y\theta \frac{\partial}{\partial x} - x\theta \frac{\partial}{\partial y} \right] \phi = \left[y\theta \frac{\partial}{\partial x} - x\theta \frac{\partial}{\partial y} \right] \mathbb{E} \phi$ ↖ ϕ

$$\frac{\hbar}{i} \pi \left[y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} \right] \psi = \frac{\hbar}{i} \left[y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} \right] \pi \psi$$

$$\pi (x p_y - y p_x) \psi = (x p_y - y p_x) \pi \psi$$

$$\pi L_z - L_z \pi = [\pi, L_z] = 0$$

L_z kommutatör.

x ve y etrafındaki dâirelere de aynıdır.

$$[\pi, L_x] = 0$$

$$[\pi, L_y] = 0$$

bulunduk

$$[\pi, \vec{L}] = 0$$

$$[\pi, L_x^2] = L_x [\pi, L_x] + [\pi, L_x] L_x = 0$$

$$\Rightarrow [\pi, \vec{L}^2] = 0$$